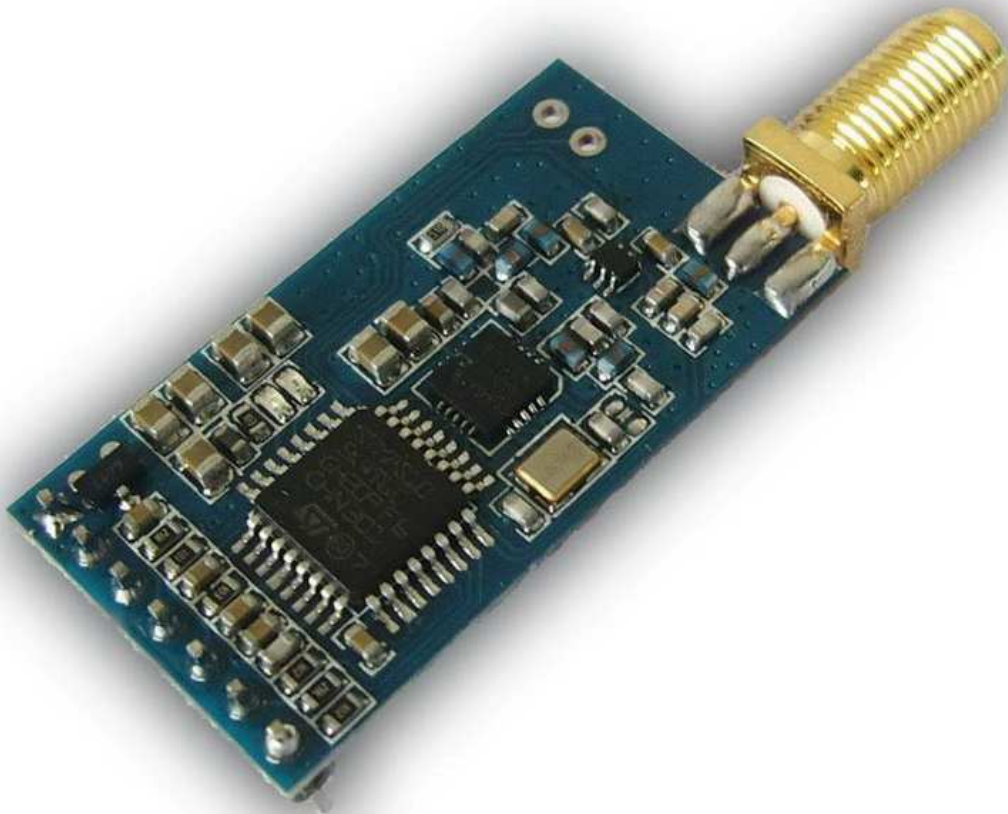


1. General

RF4463 series is a low cost, high performance transparent two way semi-duplex GFSK transceiver with operation at 433/470/868/915 Mhz. It integrates with high speed MCU from ST and high performance RF IC Si4463. Adopting high efficiency forward error correction with interleaving encoding (FEC) technology, it makes anti-interference ability and reception sensitivity greatly improved. That guarantees good performance in the harsh environment such as some industrial application. The FEC technique is advanced and unique in radio data communication field.

RF4463 has the UART interface, that make it is easy to implement wireless data transmission. It is flexible for users to set the baud rate, frequency, output power, air data rate etc parameters. It can transmit transparent data with large data buffer and also can provide over 100 channels. The compact size makes it an ideal option for radio data communication application.



2. Features

- 1800 meters of communication distance (9600bps)
- Output power: Max100mW (20dBm) (127 levels adjustable)
- Air data rate: 1200 - 57600bps, can be configured through RF tool
- UART data rate: 1200 - 57600bps, can be configured through RF tool
- Frequency: 405MHz - 440MHz, 868MHz or 915MHz
- Working Current: 90mA(TX), 15mA(RX), 3.0uA(Sleeping)
- More than 100 channels
- parity of series COM: 8E1/8N1/8O1
- GFSK modulation
- Receive sensitivity: -124dBm
- UART/TTL
- Exceed double 256 bytes data buffer
- Supply Voltage: 3.4 – 5.5V (the ripple less than $\pm 100\text{mV}$)
- Simply tool for configuration
- 250KHz Channel spacing
- Dimension: 35.0mm x 19.0mm x 7.0mm

3. Application:

- Automated Meter Reading (AMR)
- Remote control, remote measurement system
- Access control
- Access control
- Data collection
- Identification system

- IT household appliance
- Baby monitoring system

4. Maximum specification

Symbol	Parameter	Min	Max	Units
VCC	Supply Voltage	2.6	6.5	V
TOT	Operation Temperature	-30	85	°C
HOH	Operation Humidity	10%	90%	
TST	Storage Temperature	-55	125	°C

5. Pin Out:

RF4463 module has 9 pins. Refers to the Table 1:

RF4463		
Pin NO.	Pin Name	Description
1	GND	Grounding of Power Supply
2	VCC	Power supply DC 3.4V-5.5V
3	EN	Enable pin ($\cong 0.5V$): work mode; ($\cong 2.0V$) or suspended: sleep mode
4	RXD	UART input, TTL level
5	TXD	UART output, TTL level
6	AUX	Data in/out indication
7	SET	Setting Pin. Enable when Low level or connect with GND
8	NC	Not connected
9	NC	Not connected

Table 1: Pin definition

6. Dimension

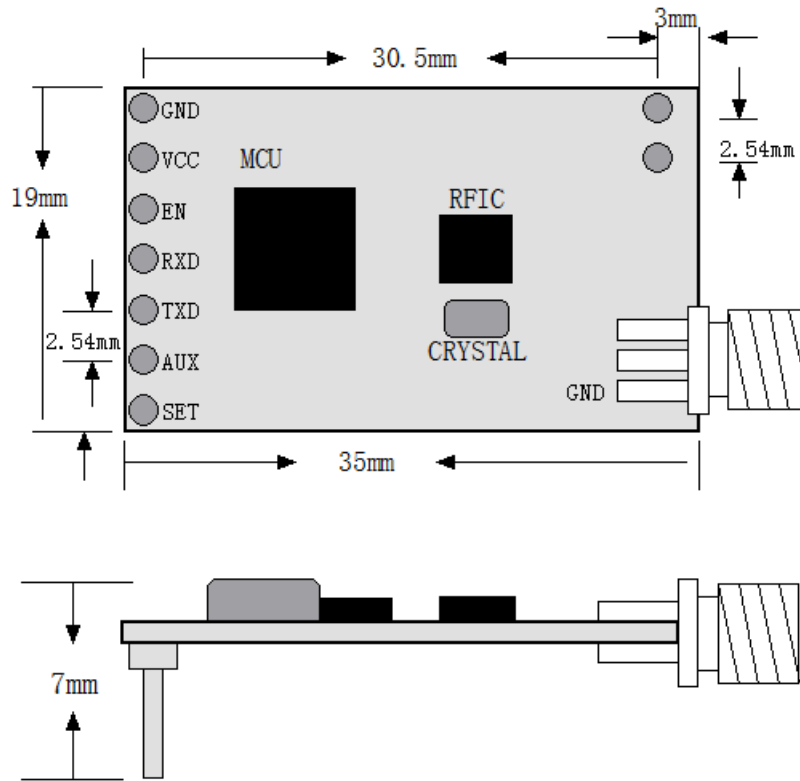


Figure 1: Size of Module

7. Parameter Configuration

Through serial port or using setting tool ‘Rf-Tool’, users can configure relative parameters such as frequency, UART rate, air rate, checkout mode and so on.

It is very simply for configuration. Based on different requirement, all options can be selected visually. It is shown in Table 2 and Figure 3.

The instruction of RF4463 parameters		
Setting	options	default
MCU data rate	1200,2400,4800,9600,19200bps	9600bps
Series Parity Check	N, 8, 1	N
Frequency	420MHz-450MHz	433 MHz
	855 MHz-875MHz	868MHz

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	900MHz-919.9MHz	915MHz
GFSK data rate	1200,2400,4800,9600,19200bps	9600bps
Output Power	0-127levels(level 127 is 100mW)	127(100mW)
Series baud rate	1200,2400,4800,9600,19200,38400, 57600bps	9600

Table 2: Parameter Specification

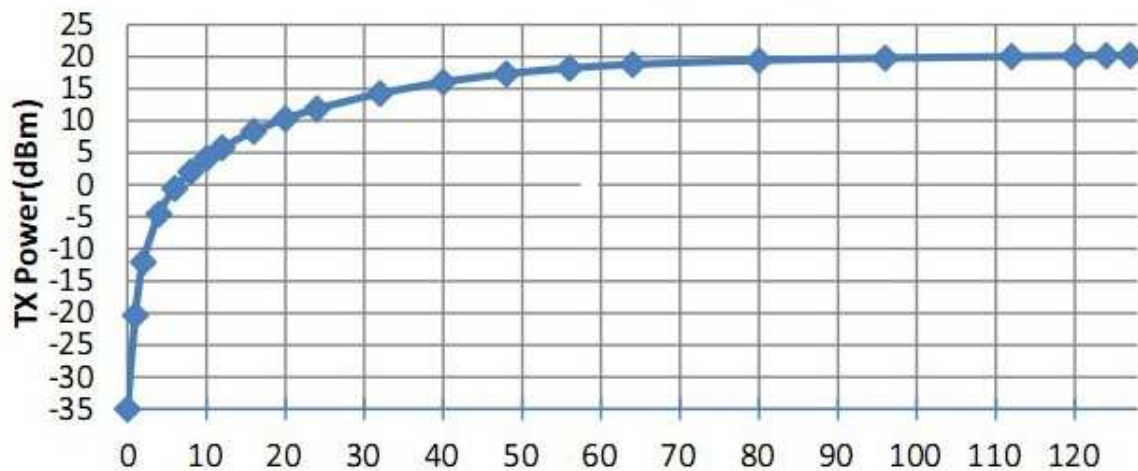
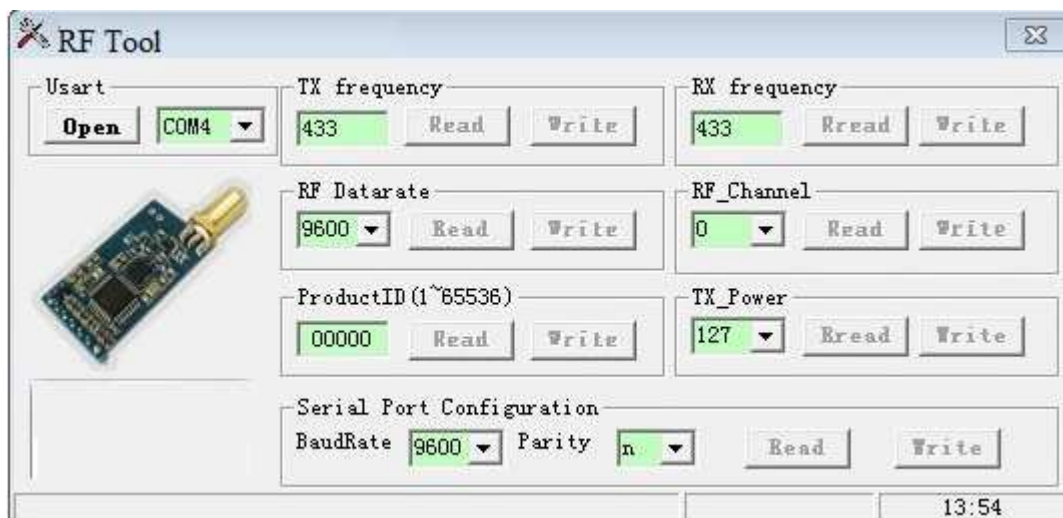


Figure 2: Indication of TX power level



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Figure 3: Interface of RF Tool

Users can configure the parameters (frequency, data rate, output power etc.) through PC or in circuit.

◆ Setting through PC. RF4463 port is UART/TTL. When RF4463 connecting with PC, users need to use USB adapter. AppconWireless provides USB adapter as accessory. The schematic is shown in Figure 4

Firstly users connect converter board to PC through DB9 cable and open 'RF Tool', then insert module into converter board. After that, the status column of 'RF tool' will give a indication 'Found Device'. Users then can read/write the module.

If users connect USB converter, USB drive "PL-2303_Driver_Installer" need be installed firstly. The drive has different version for different OS. USB converter has five wires with five different colors: Black, Red, Blue, Yellow, Green. Black wire is GND pin. Red wire is VCC pin. Blue wire is TXD pin. EN pin and SET pin should be connect to GROUND.

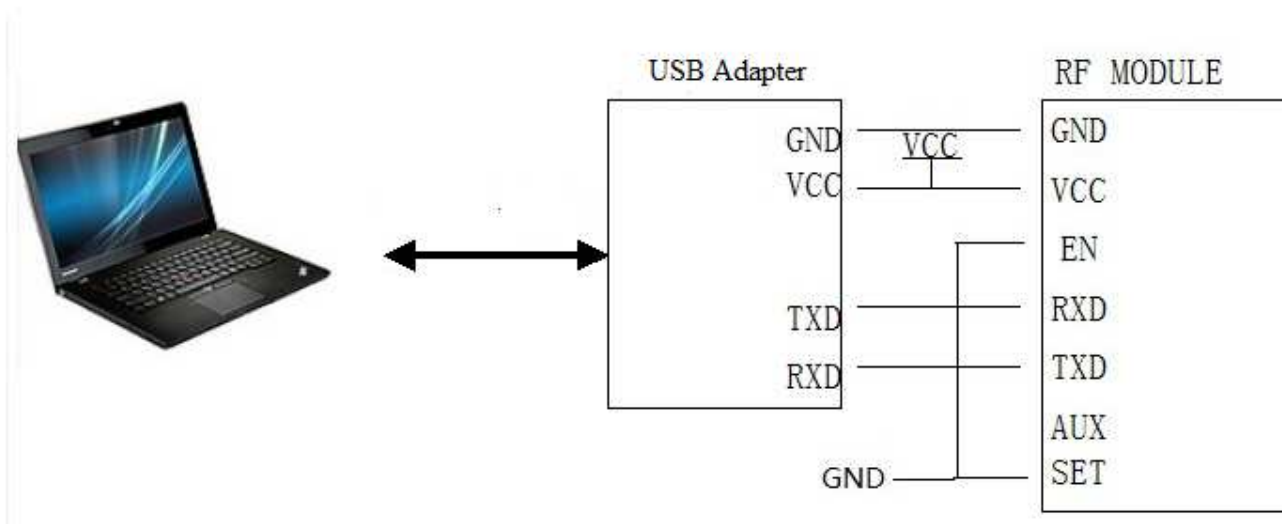


Figure 4: The connection diagram

◆ Setting in circuit . The module can work normally after powering on for 50ms (T1) or more. When

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configuring the module, users need to switch the module to sleep mode (EN pin is high or suspended) and monitor AUX pin. When AUX pin is high (no Receive or Transmit), the module will enter sleep mode in which the module can be configured after 20us (T2). When command is input to RXD pin, the module will be evoked. No matter what status of UART interface, the module will use 9600bps (data rate) and no parity check as default format to communicate.

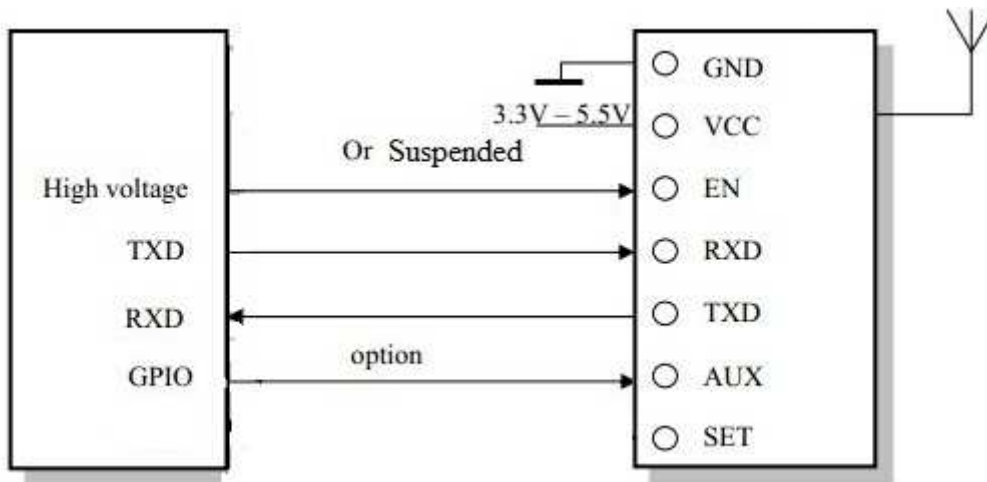


Figure 5: Connection diagram in circuit

When a command is sent to the module through the RXD pin, the module will send back response information by TXD pin in 50ms or less (T3) after it verifies the command is correct. The module then will be reset and initialized automatically and work with new settings after 100ms (T4). If the input command is incorrect, the module will make no response but it will still be reset and initialized. Users can take this advantage to wake up modules in long-term sleep or reset the modules.

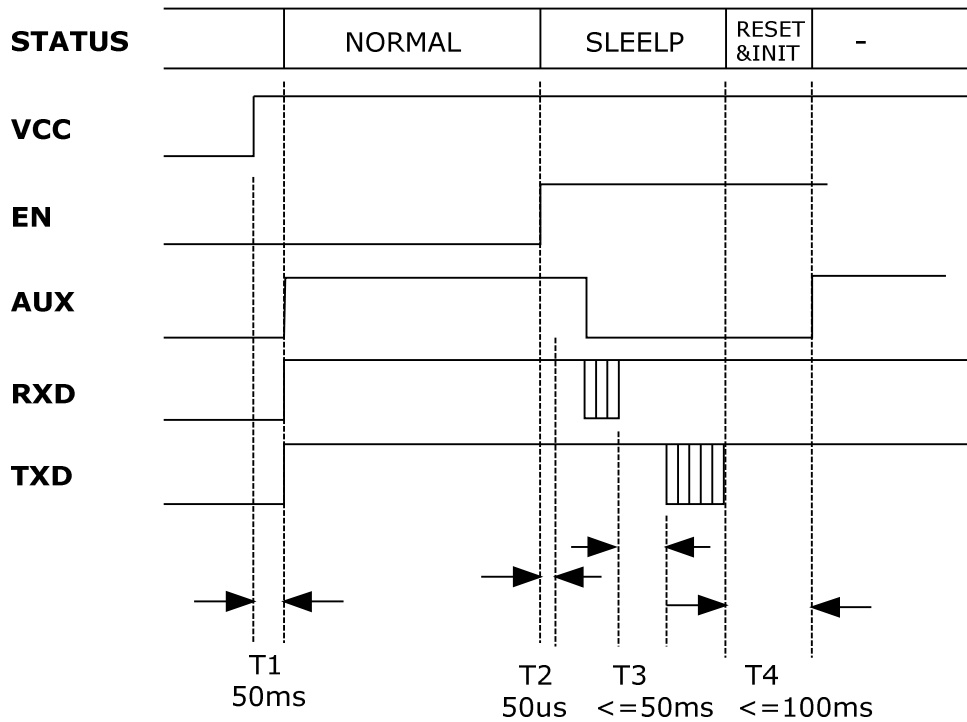


Figure 6: Timing diagram for Setting Parameters

The commands of RF4463 are in ASCII format. The default configuring data rate is 9600bps and no parity check is adopted. The command set include two commands: Read command and Write command.

◆ Read command: RD ✓

Acknowledge (from module): PARA_Freq_DR_{FSK}_P_{OUT}_DR_{IN}_Parity ✓

◆ Write command: WR_Freq_DR_{FSK}_P_{OUT}_DR_{IN}_Parity ✓

Acknowledge (from module): PARA_Freq_DR_{FSK}_P_{OUT}_DR_{IN}_Parity ✓

('_' means one blank space)

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Parameter	Unit	Length(Byte)	Description
Freq.	KHz	6	434MHz = 434000
DR _{FSK}	K bps	1	2400,4800,9600,19200 bps equal to 1,2,3,4
Pout	dB	1	0~9; 0 refers to 0dBm and 9 for 20dBm
DR _{IN}	Kbps	1	1.2, 2.4, 4.8, 9.6, 19.2, 38.4, 57.6 equals to 0,1,2,3,4,5,6
Parity		1	0: No parity; 1: Even parity; 2: Odd parity

Table 3: RF4463 Parameter Coding

E.g. If the user wants to set the module work at Freq (434MHz), DR_{IN} (1.2K bps), P_{OUT} (20dBm), DR_{FSK} (9.6k bps) and Parity (no parity), the command could be written as below:

Write Command: WR_434000_3_9_0_0

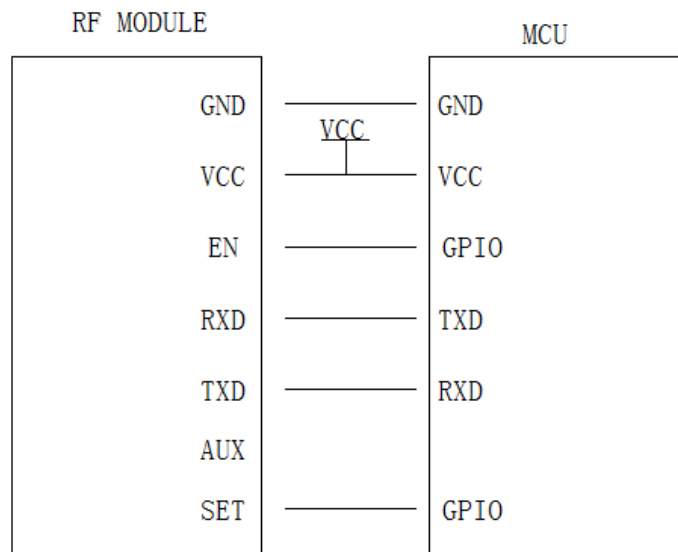
Corresponding HEX code: 0x57,0x52,0x20,0x34,0x33,0x34,0x30,0x30,0x30,0x20,0x33,0x20,0x39,0x20,0x30,0x20,0x30,0x0D,0x0A

Acknowledge: PAPA_434000_3_9_0_0

Corresponding HEX code: 0x50,0x41,0x52,0x41,0x20,0x34,0x33,0x34,0x30,0x30,0x30,0x20,0x33,0x20,0x39,0x20,0x30,0x20,0x30,0x0D,0x0A

8. Application Schematic:

The connection schematic between RF4463 and MCU or terminal is shown as below. If users do not need sleep mode, EN pin could be connected to GND directly. If users need to configure parameter in circuit via AT command, SET pin must be connected to GND. When RF4463 is in Receive or Transmit mode, SET pin must be suspended or connected with high level. The parameter of RF4463's serial port must match with MCU or terminal's (RF4463 has the same serial port baud rate and parity style with MCU or terminal). Two or more RF4463s in a system should have the same parameters such as TX/RX frequency, air data rate and RF channel.



- Caution:**
- 1, When RF4463 connect the UART/TTL interface, SET pin must be suspended or in high level.
 - 2, RF4463 should have the same common ground with MCU or terminal. Otherwise it may cause the module irregular working.
 3. When RF4463 works normal, DO NOT touch the module and antenna.

Figure 7: The Connection between Module and Device

9. Constructing Network (one point to multi-point):

RF4463 is a semi-duplex module, which can be communicated by point to point or one point to multi-point. In the second mode, user needs to set one master module, while the others are slave modules. Every module must only have one unique ID. The coordination of communication is controlled by the master module, which sends data or commands including ID information. All slave modules can receive the data packets, and compare the ID with itself. If they are matched, the module will deal with the data packets. Otherwise, it will discard them. In order to avoid interfering each other, only one module can be in transmitting state when the network is working. RF4463 can set many different frequencies so that many networks can work in the same place and at the same time.

User should pay attention to the following questions based on the complex transfers in the air and some inherency characteristics of wireless communication:

1) Latency of wireless communication

The wireless terminal keeps receiving data packets after waiting for a while to ensure no data any more. There should be tens to hundreds mil-seconds latency from transfer to receiver (the exact latency depended on UART rate, air rate and the size of data package). In addition, it also need consume some time to transmit from module to terminal, but the delay time is permanent in the same condition.

2) Data flux control

Although there is a buffer zone with 256 bytes in the wireless module, when the UART rate is higher than the air rate, there must be a problem about the data flux. It may cause to lose some data because the data overflow from the buffer. Under this condition, it must be ensured that the average UART rate should NOT higher than 60 percent of the air rate. For instance, the UART rate is 9600bps, the air rate is 4800bps. If UART rate is the same as the air rate, the only way is to interval the transmitting time. If terminal transmits 100bytes to UART every time, it will take 104ms every time. $(104\text{ms}/0.6) \times (9600/4800) = 347\text{ms}$. So if the interval time that terminal transmit 100bytes to UART should NOT less than 347ms every time, those mentioned problems can be avoided.

3) Error control

The wireless network module has strong capability of anti-interference because of the high efficiency

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checking error correction with interleaving encoding technology. However, when it is in a bad circumstance that has strong electric interference, the data may be lost or receive some error data. User can increase the development of the system link layer protocol. For instance, if user can increase TCP/IP slip window and repeat transmitting functions, it will improve the reliability and ability of wireless network communication.

4) Selection of antenna

Antenna is a very important factor of the communication system. The quality of antenna impacts the capability of communication system. So user should strictly choose the quality of antenna. Generally speaking, it mainly contains two points: the type of antenna (size) and its electric capability. The antenna must be matched with the frequency of communication system.

10. Q&A:

Questions and Answers	
Can not communicate between two devices	1. The communication protocol is different between two modules, for instance: data rate and checkout.
	2. The frequency or RF data rate is different between two communicated modules.
	3. They are not the same kind products.
	4. The connection between module and terminal is wrong.
	5. The module is wrong.
	6. The setting of EN is wrong.
	7. The communication distance exceeds the range, or the connection of antenna is bad.
Short communication distance	1. The supply voltage exceeds range
	2. The ripple of power is too big.
	3. The connection of antenna is bad or it is a wrong kind of antenna
	4. Antenna is too close to the surface of metal or the ground

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	5. Receiving circumstance is very bad, for instance buildings and strong interference.
	6. There is interference of the same frequency
Receive wrong data	1. Wrong setting of COM, for example, Baud rate is wrong
	2. The connection of UART is wrong.
	3. The cable to the UART is too long.

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